

Vision for MUSICC

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Principal Technologist | 24th June 2019

The challenge



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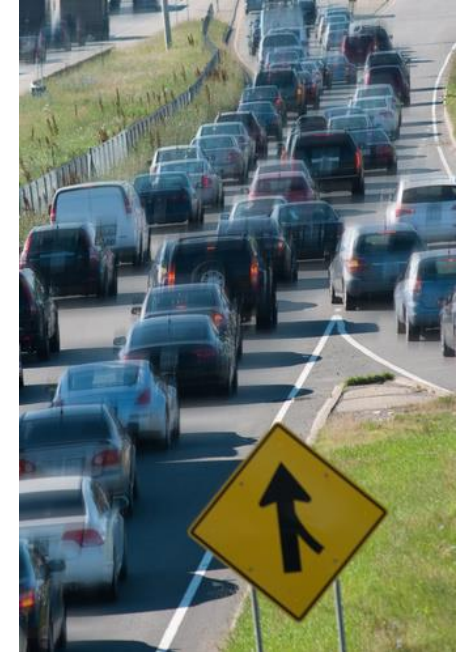


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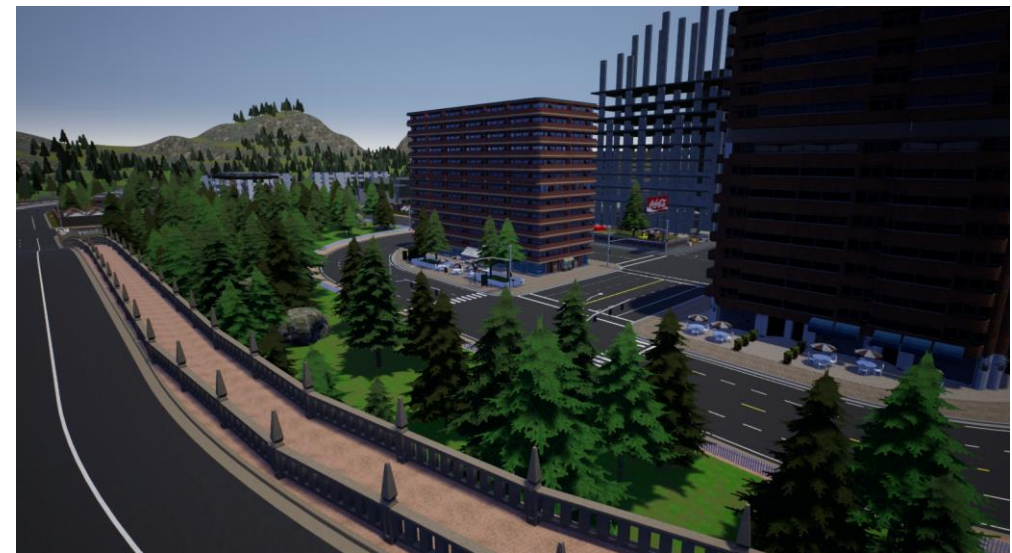
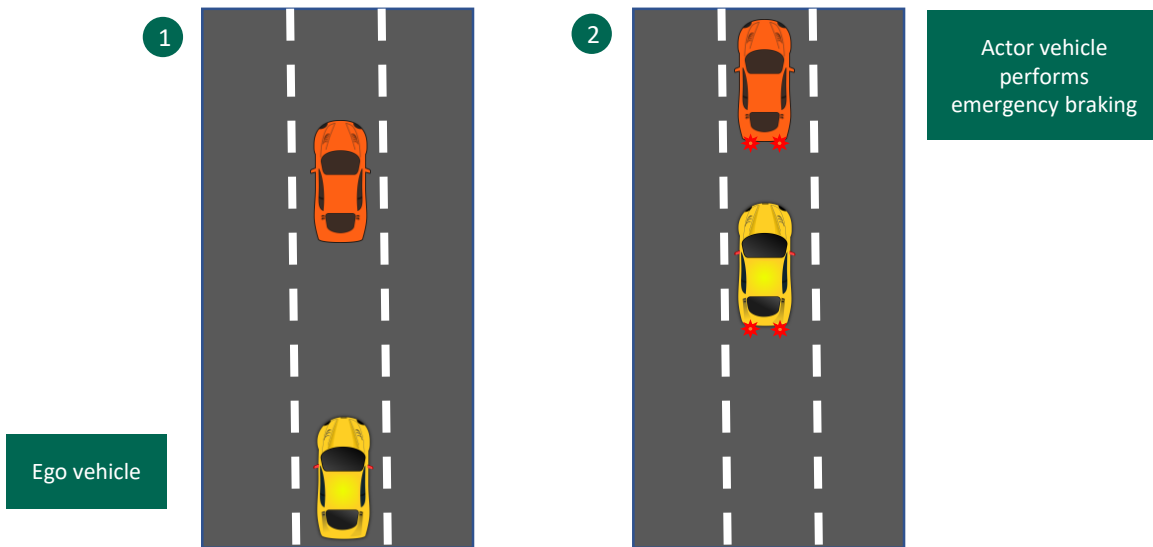
Why is HAV verification hard?

- An automated driving system (ADS) is far more complex than previous automotive cyber-physical systems
- It must cope with:
 - chaotic behaviour of other road users
 - complex junctions, variability in roads
 - weather and perceptual challenges



Solutions for HAV verification

Can't test on public roads: "To demonstrate that fully autonomous vehicles have a fatality rate of 1.09 fatalities per 100 million miles [...] with a fleet of 100 autonomous vehicles being test-driven 24 h a day, 365 days a year at an average speed of 25 miles per hour, this would take about 12.5 years."¹

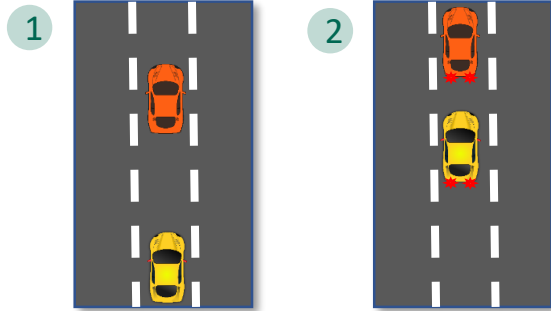


Scenarios: avoid uninformative testing

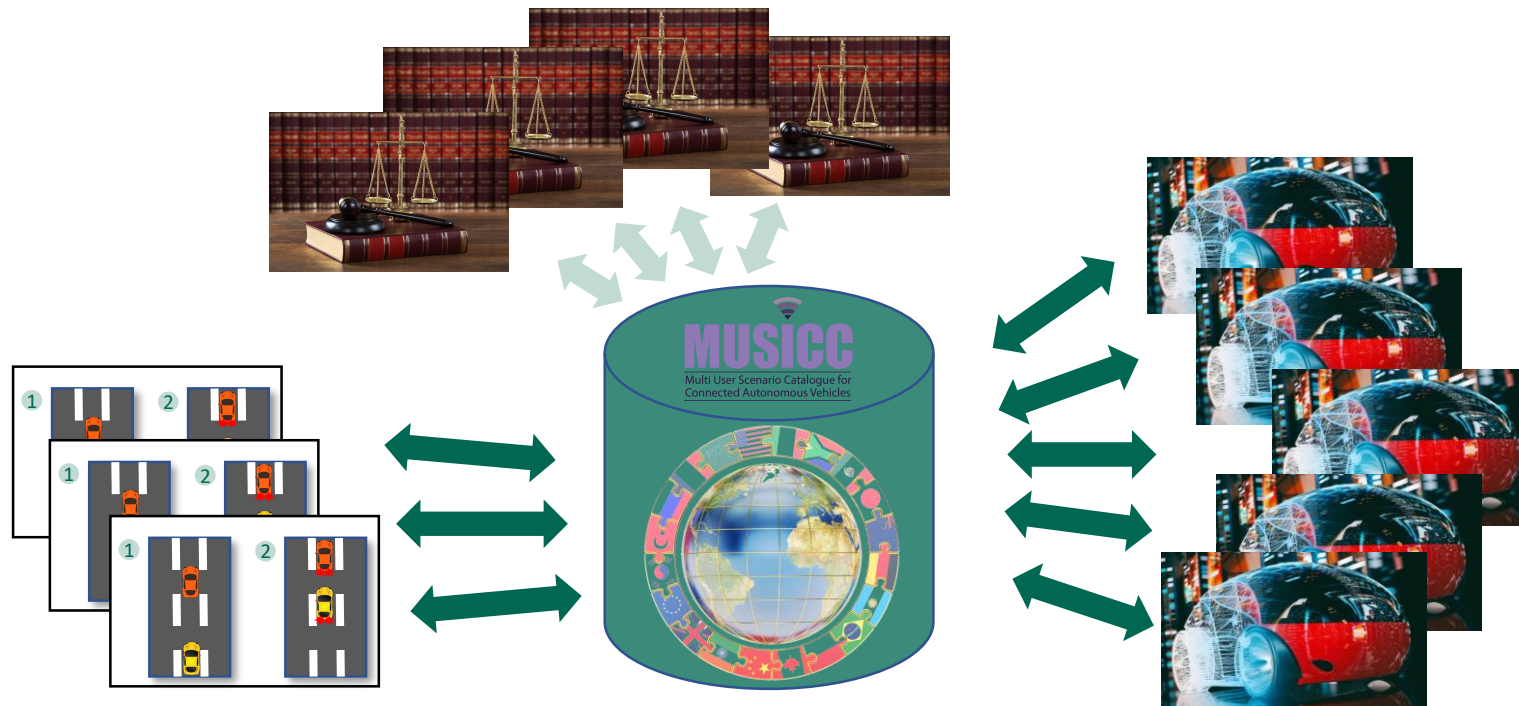
Simulation: run tests much more efficiently

¹ "Driving to safety: How many miles of driving would it take to demonstrate autonomous vehicle reliability?"
Nidhi Kalra & Susan M. Paddock, RAND Corporation 2016. https://www.rand.org/pubs/research_reports/RR1478.html

What does this mean for regulation?



- Traditionally regulations specify a concise, explicit performance standards
- Most stakeholders are clear that scenarios represent the most effective way of specifying the test cases for certification
 - Given enough scenarios at the right level of abstraction, almost all cases can be captured



Objectives and approach



Multi User Scenario Catalogue for
Connected Autonomous Vehicles

Approach:

- Proof-of-concept project, Apr 2018 – Mar 2020
- Close collaboration with vehicle manufacturers, ADS developers, organisations with expertise in HAV validation, and regulators

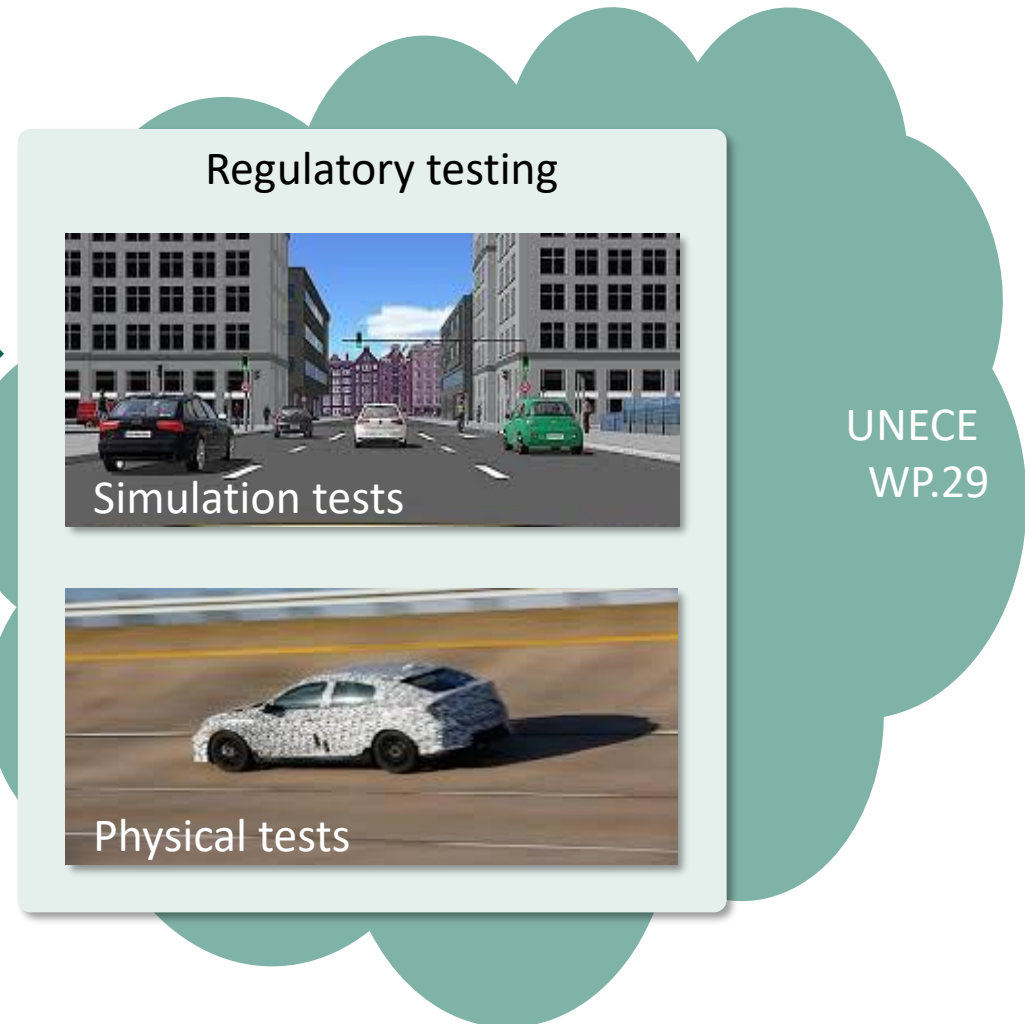
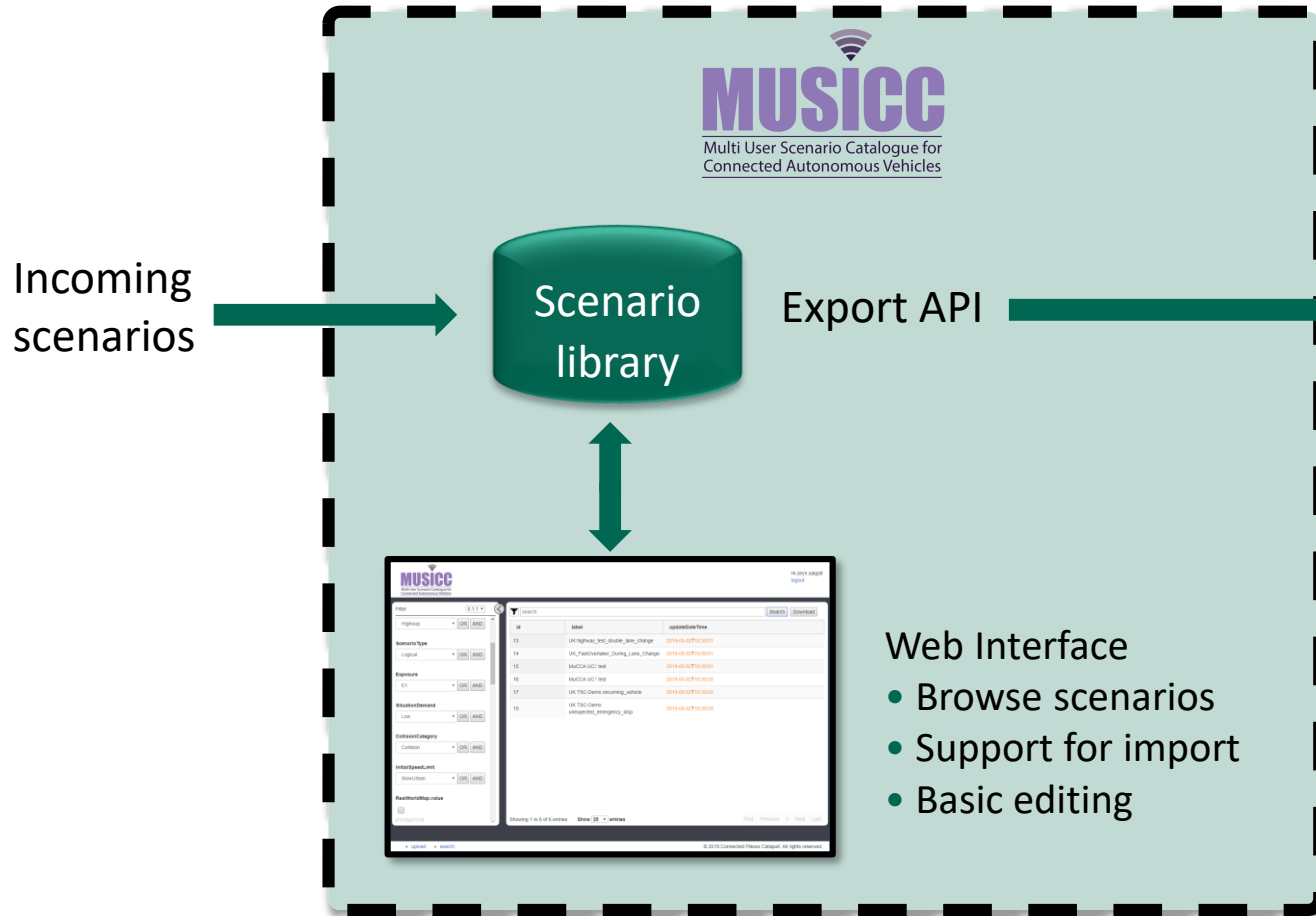
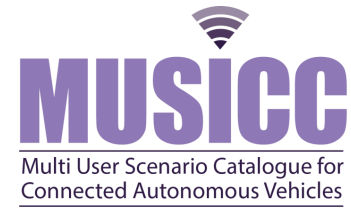
Objectives:

- Create a language to describe scenarios, aligned with industry standards
- Build an open, online library for HAV certification scenarios

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MUSICC scope and context



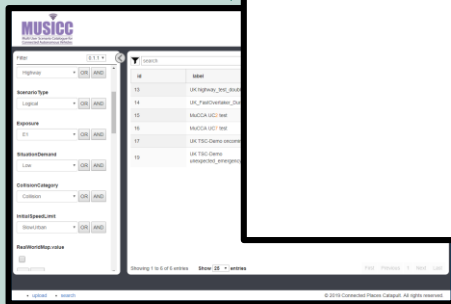
MUSICC scope and context

- We've now built this
- Our philosophy is to learn-by-doing
- Some of the doing and learning must come from the community!

Incoming scenarios



Scenario library



• Basic editing

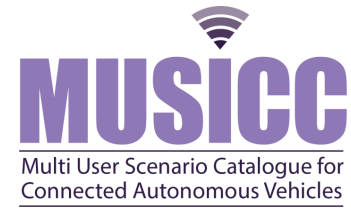
Virtual testing



Physical tests

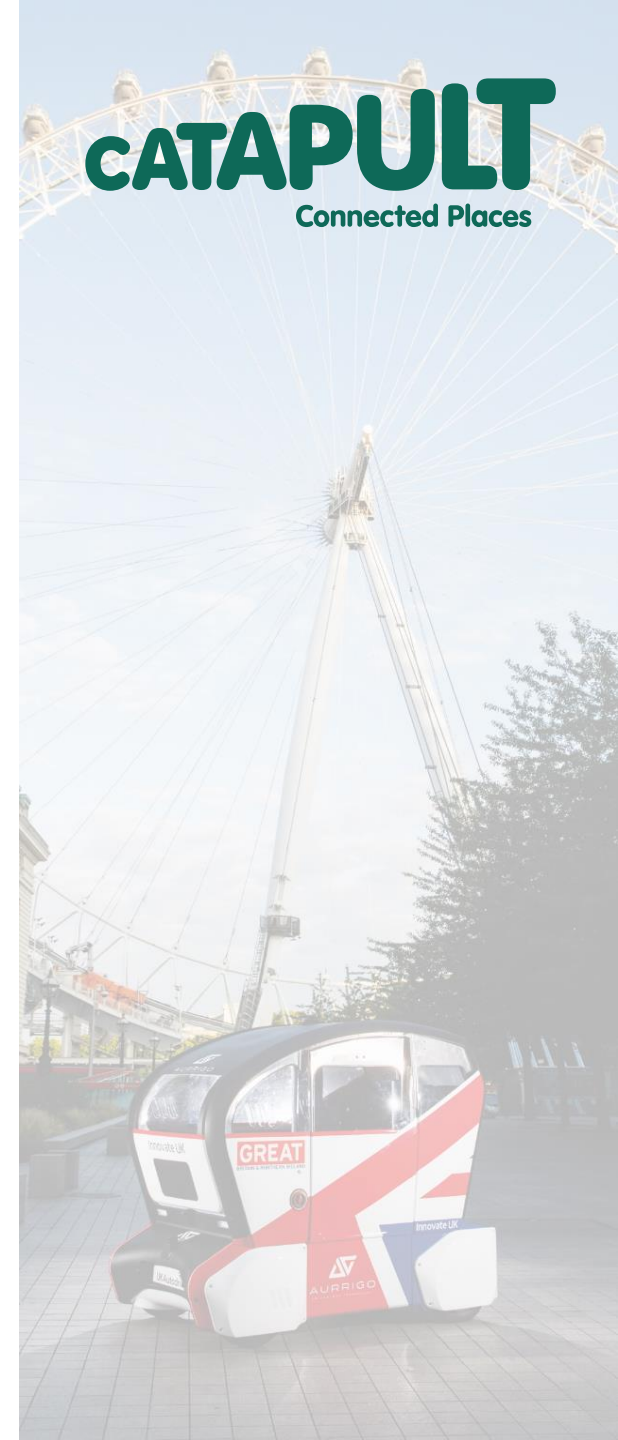
UNECE
WP.29

Step 1: Create a common scenario format



The Scenario Description Language (SDL) is a key part of MUSICC's deliverables.

- Defines a format for representing scenarios (fields and data structures needed)
- Stakeholders will be more willing to engage if a standardised or widely-compatible format is used

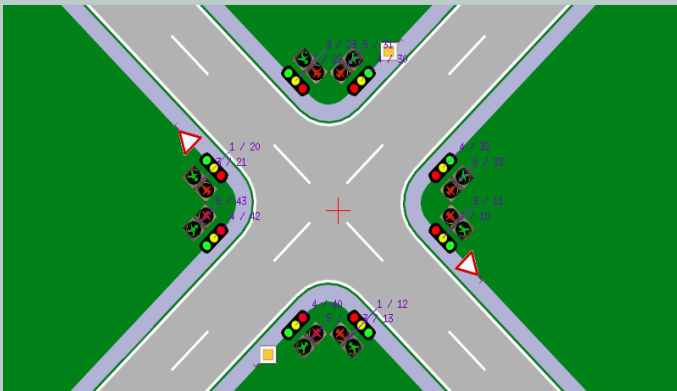


MUSICC scenario description language

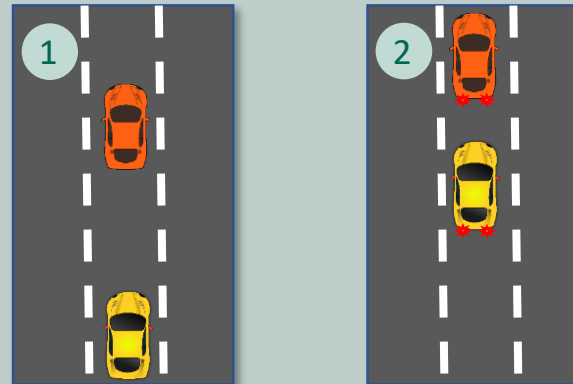
MUSICC Scenario Record

- Metadata
- Parameter stochastics
- Ego goal
- 3D models

OpenDRIVE Record



OpenSCENARIO Record

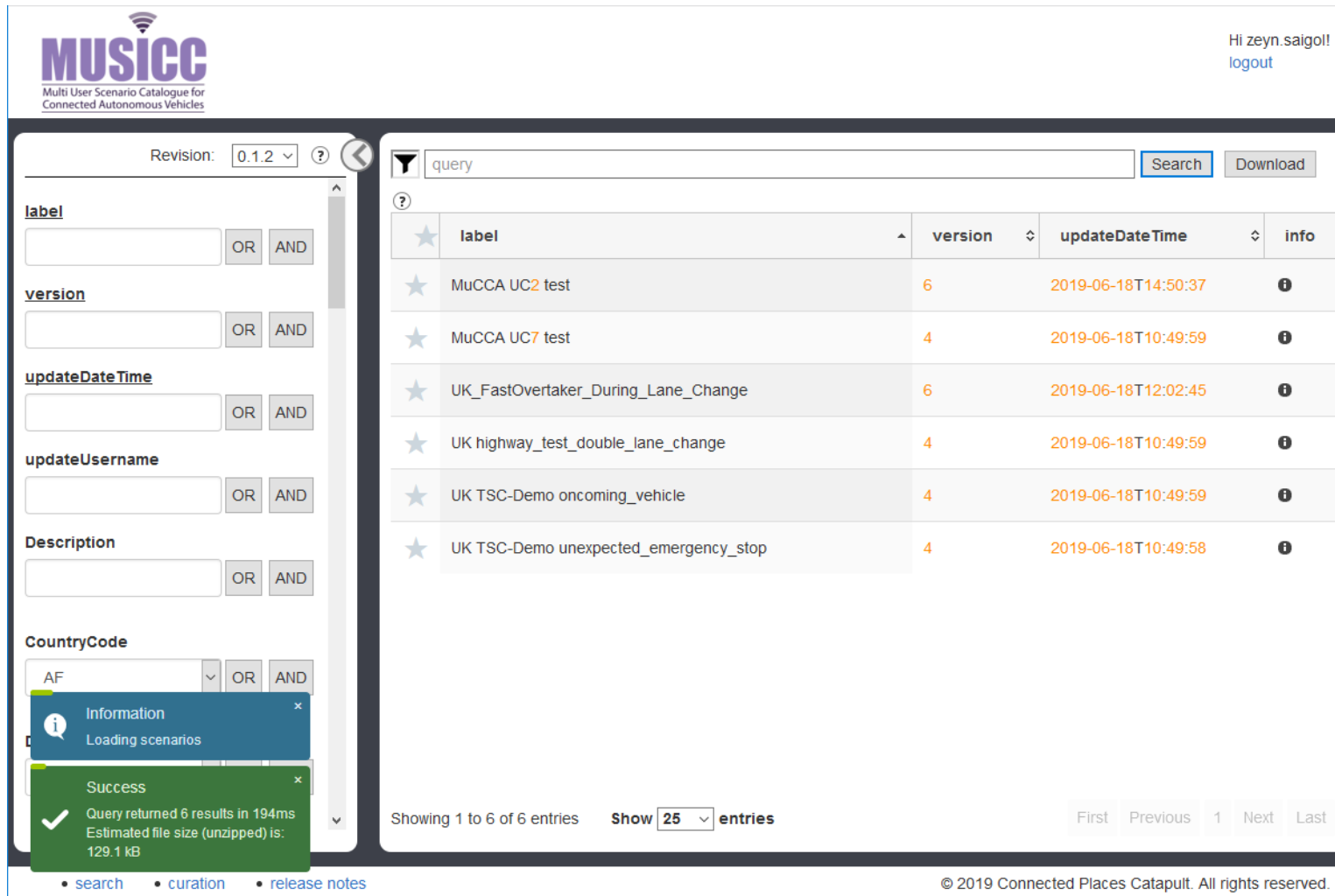


The SDL has been developed based on:

- Stakeholder input, especially the September 2018 MUSICC workshop
- Industry-standard formats (ASAM OpenX)

Step 2: Create a online DB system

To be demoed this afternoon...



The screenshot shows the MUSICC web application interface. The top left features the MUSICC logo and the text "Multi User Scenario Catalogue for Connected Autonomous Vehicles". The top right shows the user "Hi zeyn.saigol!" and a "logout" link. The main content area is divided into a left sidebar and a main table.

Left Sidebar (Filters):

- Revision: 0.1.2
- label: [input field] OR AND
- version: [input field] OR AND
- updateDateTime: [input field] OR AND
- updateUsername: [input field] OR AND
- Description: [input field] OR AND
- CountryCode: AF [dropdown] OR AND

Main Table (Search Results):

| ★ | label | version | updateDateTime | info |
|---|---------------------------------------|---------|---------------------|------|
| ★ | MuCCA UC2 test | 6 | 2019-06-18T14:50:37 | i |
| ★ | MuCCA UC7 test | 4 | 2019-06-18T10:49:59 | i |
| ★ | UK_FastOvertaker_During_Lane_Change | 6 | 2019-06-18T12:02:45 | i |
| ★ | UK highway_test_double_lane_change | 4 | 2019-06-18T10:49:59 | i |
| ★ | UK TSC-Demo oncoming_vehicle | 4 | 2019-06-18T10:49:59 | i |
| ★ | UK TSC-Demo unexpected_emergency_stop | 4 | 2019-06-18T10:49:58 | i |

Bottom of Table: Showing 1 to 6 of 6 entries. Show 25 entries. First Previous 1 Next Last

Notifications:

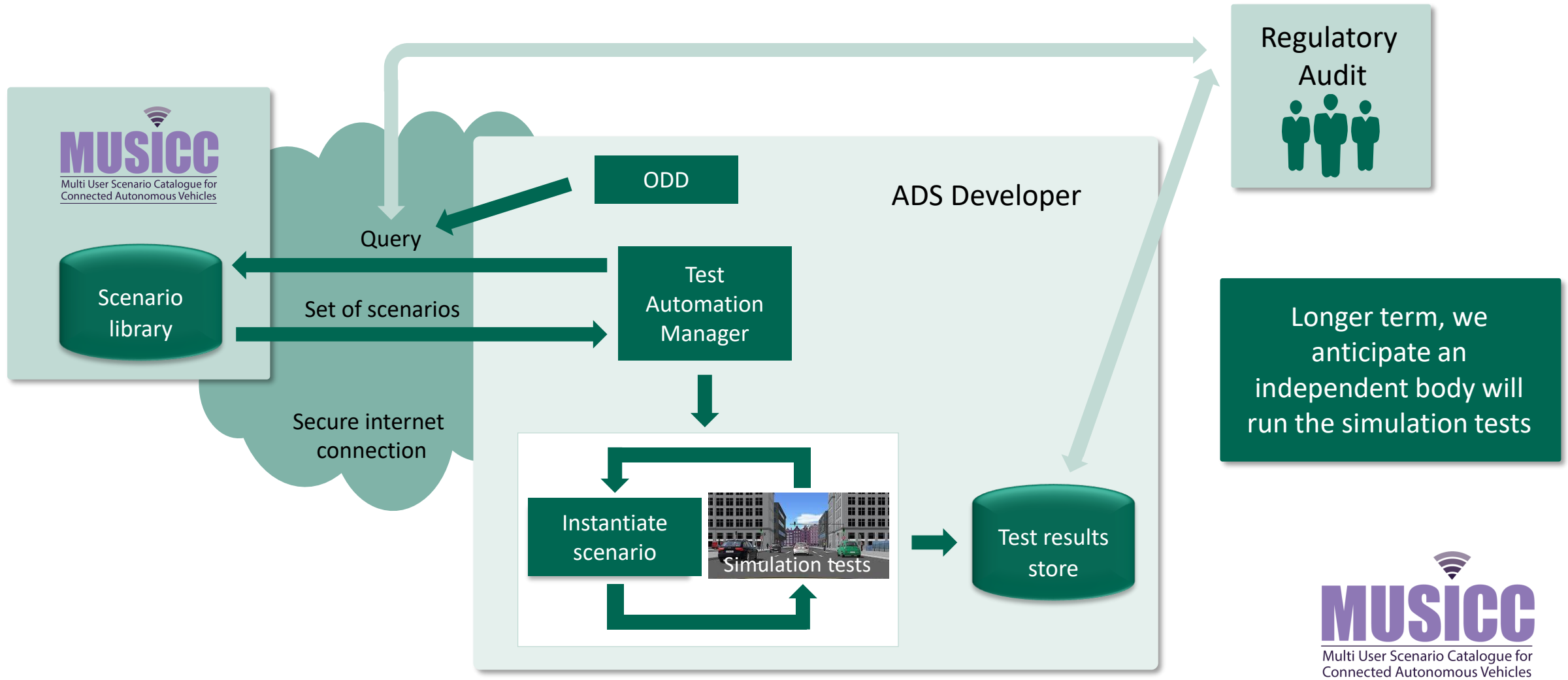
- Information: Loading scenarios
- Success: Query returned 6 results in 194ms. Estimated file size (unzipped) is: 129.1 kB

Footer: • search • curation • release notes

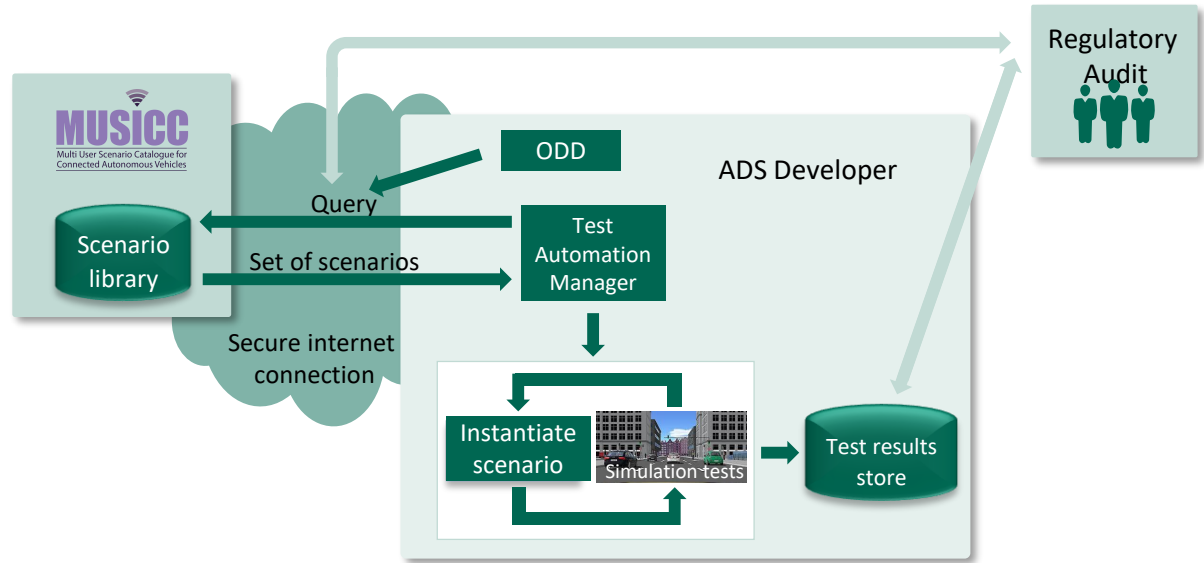
What is the vision for MUSICC?



Help bring a certification framework to life



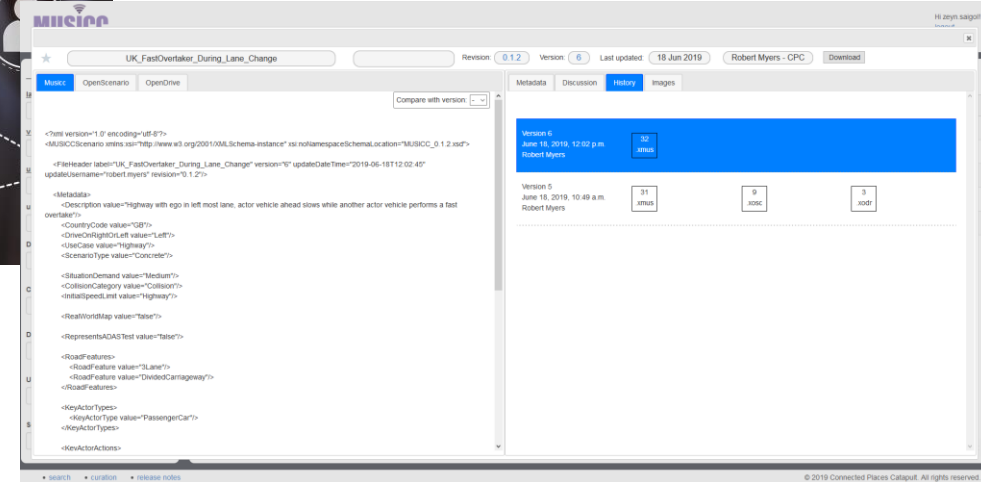
MUSICC vision



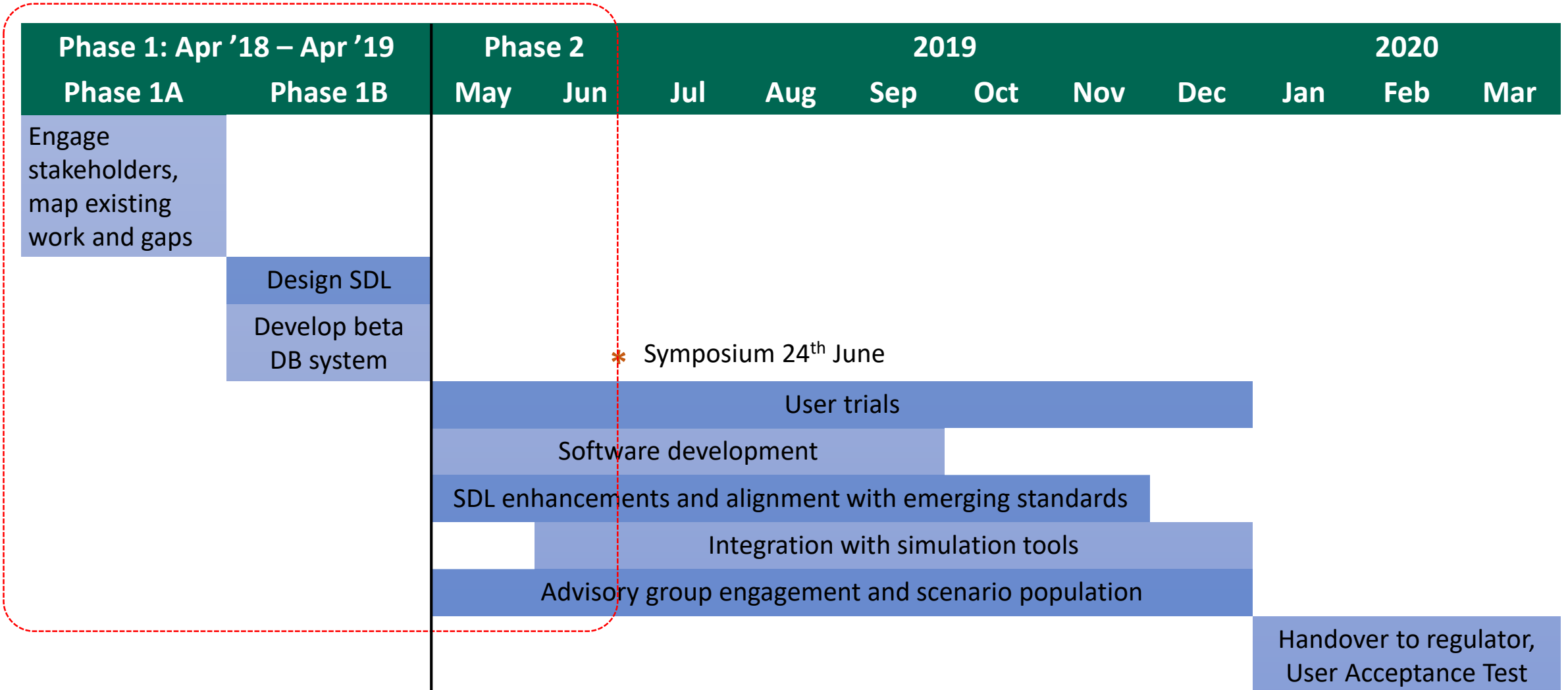
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Connected Places

MUSICC
Multi User Scenario Catalogue for Connected Autonomous Vehicles



Timeline and plans



Scene setting for independent certification

- For example, US culture is to minimise regulation and rely on market forces

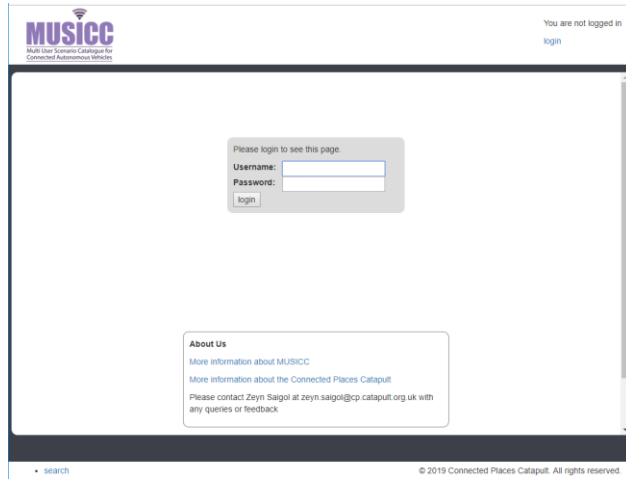


- Mary Schiavo, former Inspector General at the US DoT, on the FAA:
“They pretend to inspect, and Boeing pretends to be inspected, when in fact Boeing is doing it all almost entirely by itself”¹
- US senator Richard Blumenthal said the FAA had:
“put the fox in charge of the henhouse”¹

¹ “What went wrong inside Boeing's cockpit?”

Theo Leggett, https://www.bbc.co.uk/news/resources/idt-sh/boeing_two_deadly_crashes

User Trials: Invitation



The MUSICC system is officially open for beta users!

User trials will run until 29th Nov 2019.
To register, please email:
musicc-support@cp.catapult.org.uk

- Key benefit for participants is the chance to **influence the end shape of MUSICC**, and therefore indirectly influence the UK and UN's future CAV regulatory framework
 - Especially in terms of scenario formats and interoperability
- For the MUSICC team, our aim is to ensure we're building something that is both effective and acceptable to the community

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Multi User Scenario Catalogue for
Connected Autonomous Vehicles

Thank you for your attention



is supported by



Department
for Transport

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