

Autonomous systems and Hangar of the Future

Luca Zanotti Fragonara

Centre for Autonomous and Cyberphysical Systems

17th October 2019

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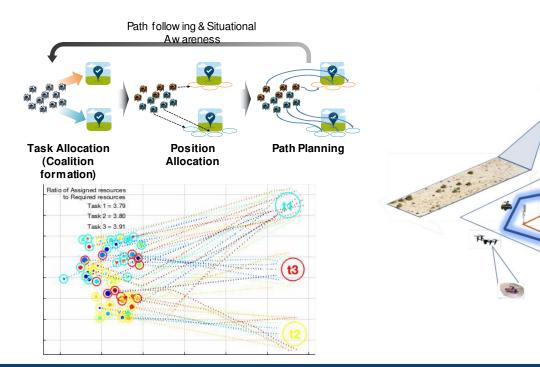


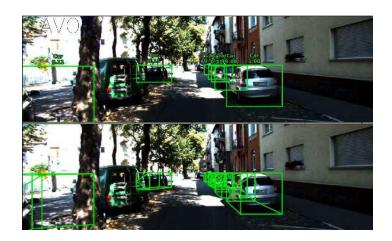
Autonomous Systems

- Perception: detection with deep learning models, multi-target tracking and data association.
- Sensor Fusion architectures (distributed architectures).

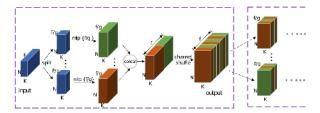
- Alt

Task allocation.





ShufflePointNet



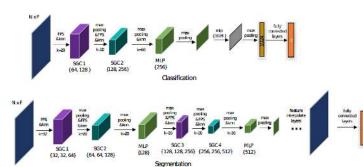


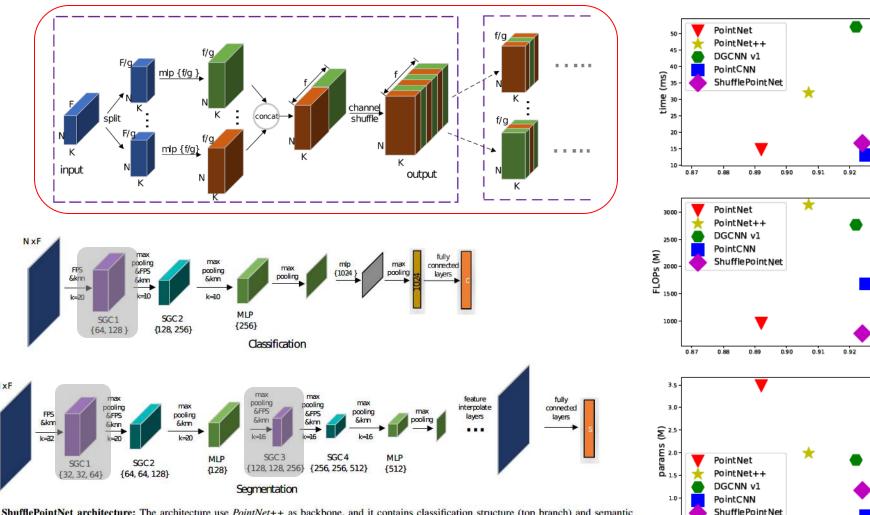
Fig. 3. ShufflePointNet architecture: The architecture use PointNet++ as backbone, and it contains classification structure (top branch) and semantic segmentation structure (bottom branch) for point cloud. In detail, N, F indicates the number of inpat points, and corresponding feature channels respectively, *k* is the number of the neighbors. Besides, the number in the brance {} indicates the MLP filters.

ShufflePointNet: An Efficient Neural Network for Point Cloud Analysis via Group Convolutions

 ShufflePointNet is an efficient way to process point-cloud data

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- Uses the concept of channel shuffle and shuffle layer
- A state-of-the-art deep neural network capable of reaching high-level accuracy for segmentation and classification
- Efficient computational performance



0.5

0.87

0.88

0,89

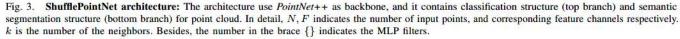
0.90

accuracy (%)

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0.91

0.92





Hangar of the future

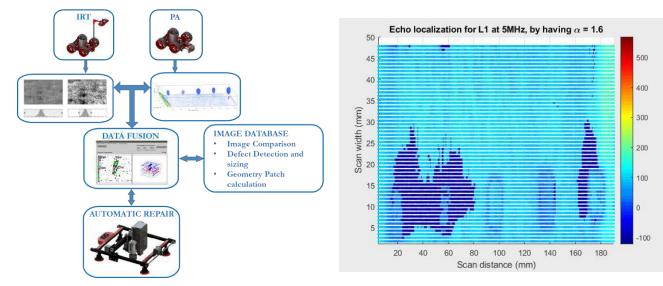
- Automated inspections
- Sensor fusion
- Data analytics
- Predictive maintenance



UAV inspection (using RGB or IRT cameras)



Robo-inspections (Ultrasonic + IRT)





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Using data analyse patterns

TTT PROGNOSTICS

- Replacement of unscheduled maintenance by systematic scheduled maintenance
- A Replacement of scheduled maintenance by condition based maintenance

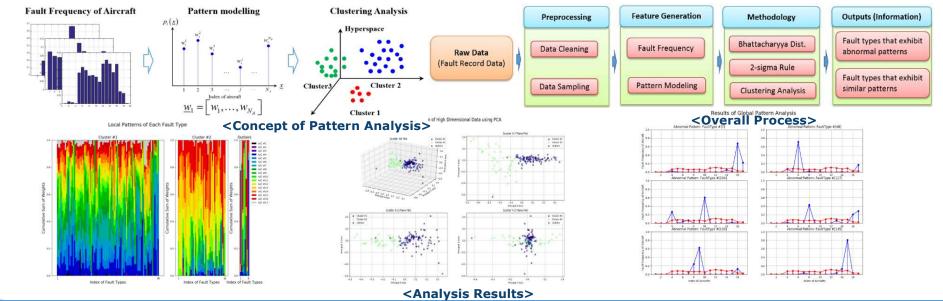






Pattern Analysis

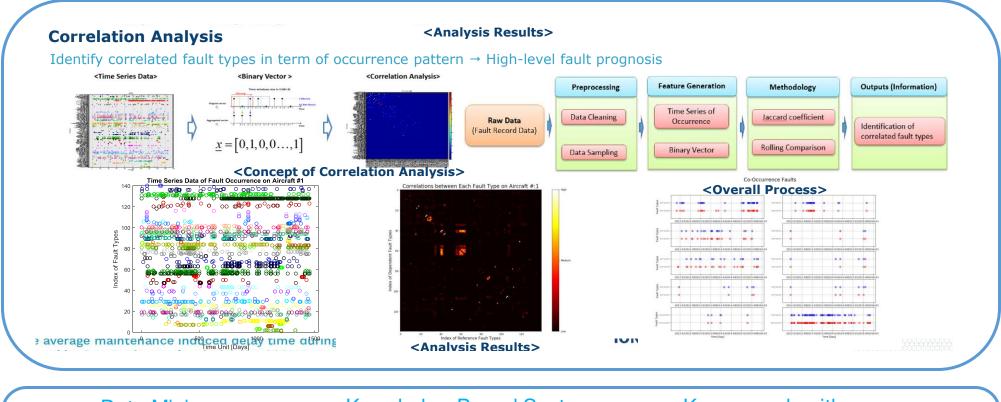
Identify unusual patterns of fault frequency across the fleet aircraft \rightarrow Early warning for potential issue





Using data to predict failures





Data MiningKnowledge Based SystemK-means algorithmMachine LearningDecision TreesSupport Vector MachineDensity-Based ClusteringSelf-Organizing MapHill Climbing Algorithm